

Mike driver

M-665.2PM inear translator with

50 mm travel range

iezoelectric linear drive

and adaptor box for use

with standard PI moto



The new PI catalog, MicroPositioning, NanoPositioning, NanoAutomation, Solutions for Cutting-Edge Technologies is now available. In addition to the comprehensive product information familiar from previous editions, the new work features an application-oriented approach which will make it easier to find the product group that fits vour needs. Just click on the new catalog on our homepage (www.pi.ws) or order your free printed copy today. Spend some time just browsing through the 400 pages in 9 sections. The catalog is currently available in English only, but a German version is in preparation.

The best catalog or Internet presentation, however, can never replace a talk with one of our representatives about your particular situation. A large portion of our sales are to OEMs, and many are products customized to meet special requirements.

# Piezo Motor Kick-Off

PI has been working on piezo-electric motor development for a long time. Now we are able to introduce two products:

#### PiezoMike

The PiezoMike is a non-rotating-tip micrometer driven directly by a piezoelectric rotary motor. The unit is controlled via a manual control pad.

Advantages of the piezo motor design:

- Direct drive with no gearing
- High holding force when powered off
- Excellent start/stop behavior
- Smooth and quiet motion
- No magnetic fields.

The piezo motors can execute steps of about 0.5 µm as easily as continuous motion at up to 2 mm/s. Because the PiezoMike is an open-loop system, it is more suited to applications involving rapid, remote-controlled adjustments than for high reproducibility.

Turning the micrometer spindle manually at any time is also permissible. And if you happen to run into the hard stop, no problem! Just back off in the other direction.

PiezoMike-a robust and easy-to-use adjusting tool, with travel ranges of 10, 25 and 50 mm.

Translation stage with integrated piezo linear-motor drive You may have seen this unit at LASER 2001 in Munich. Its main trump lies in its compatibility with PI motor controllers.

There are big differences in the mechanics: no drive spindle, enabling a much flatter design, different control behavior and all the characteristics that set piezo motors apart. But you can use the same proven PI motor controllers as with other PI stages. The stage has the



The maximum speed of 50 mm/s is currently limited by the controller. It should soon be possible to increase this to 200 mm/s.

In the coming months, PI will be integrating piezo motors into other stages, some specially designed to fit the motor and others reflecting current, well-known stage geometries.

#### The smallest piezo motor

The adjacent illustration shows the prototype of a piezoelectric rotary motor with a through shaft and a diameter of only 3 mm!! The motor is planned for application as a drive unit in microsystems technology. The prototype shown can provide a torques of up to 0.4 millinewton meters.

Customer-specific problems in which limited space makes conventional solutions inappropriate will increasingly result in new developments being introduced.

We are willing and able to solve your problems

We have all the required components under our contro

working principles, protected by our own patents.

from the piezoelectric ceramics, the electronics and the



Miniature piezoelectric rotary motor.

The successful NanoCube™ series of XYZ NanoPositioners has been widened to include several new versions

By its compact design, 100 µm travel range in 3 axes and high resolution, the P-611 NanoCube™ has found rapid acceptance for the most varied of positioning tasks in fiber optics and photonics packaging. To better meet the specialized requirements in the fiber-optics area, models with integrated fiber holder interface are being offered. The P-611.3SF and P-611.3OF allow direct mounting of the P-603.xx fiber, objective and waveguide holders. A model for highest flexibility with a crossed fiber holder interface is planned.



ble controllers, such as the PC card (E-760), the desktop E-664.S3 and the modular E-500-series electronics, allow easy adaptation of the piezo system to the most varied of requirements. With the E-760 PC-card and the F-206 fibercoupling Hexapod or

The different compati-

NanoCubeTM: Compace C-880 controller, the P-611 Nano-XYZ NanoAliq system with 100 µm travel Cube™ becomes a multi-axis posirange in each axis and tioning system with long travel ran-

catalog or visit **www.pi.ws** 

1 nm resolution, shown here with the F603.22 fiber-holder ferrule. For more information on this product, see pages 2-36 and 8-18 in our 2001 catalog or visit www.pi.ws

High-resolution electron microscopy is finding more and more use in quality control and research applications. Here there is need for high-resolution positioners capable of vacuum operation. The P-611 NanoCube<sup>™</sup> is thus available in a vacuum-compatible version for pressures down to 10<sup>-6</sup> hPa. For processes where magnetic properties play a role. Pl also offers versions made completely of non-magnetic materials.

#### H E A D Q U A R T E R S

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# P-611 Nanocube<sup>TM</sup> New Stepper-Motor Controller:

Pl's C-600 stepper-motor controller opens a new dimension in precision positioning and trajectory control. This 4-axis controller was specially developed for automation tasks, precision measurements and general positioning in both research and industrial settings. Resolution of up to 20,000 steps per revolution make sub-micron accuracy and path control possible

Motor Types 2- and 4-phase stepper motors,

50x microstep (20,000 steps/rev

Trapezoid, linear interpolation circular, helix

8 digital I/O lines, limit switch

MotionBasic developme

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PI-Polytec Co. Ltd.

2x16 LCD display

24-kev kevpa

Operating Voltage 85-240 VAC, 50-60 Hz

Motor Current 0.1 to 1.5 A

Analog input 2 channels

Trajectories

terface

rogramming

Manual Input

Equipped with a high-performance. 32-bit processor and a multi-tasking operating system, all four axes can achieve step-for-step coordination and accuracy. The C-600 offers 2-D and 4-D linear, circular and helical interpolation, as well as the ability to operate simultaneously in more than one coordinate system. Together with high-precision stages like the M-511.2S, you can trace circles with radii of a few microns.

The C-600 can be operated using either the front-panel keypad or the serial port. The keypad functionality can be programmed by the user. The convenient MotionBasic development environment makes it possible for programmers and non-programmers alike to create simple programm sequences and to download them to the C-600. Windows programmers can make use of the comprehensive function libraries for all Windows platforms. The MotionBasic development environment is a combination of a practical programming language with the G-code programming used for CNC machines

All these features make the C-600 an extremely versatile controller which combines the advantages of an SPC system with the simplicity of a PCprogrammable motor controller.

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# NEWS Movement Positioning

#### Issue 1/2002

#### **EDITORIAL**

#### Dear Reader,

There have been a number of changes since the last issue of this newsletter.

#### We have moved!!

Only three kilometers, to be sureand literally within sight of our previous location—but still an important step for Pl.

The Production, Engineering and Purchasing Departments have been working at the new site since July. Sales, Development and

Administration joined them in the last week of October.

Thanks to the best of preparations and the dedication of our staff, the move went so smoothly that you, our customers, probably did not even notice.

Now with more room, new measurement and tesing facilities, more personnel and even higher motivation, we are there to serve you from our new headquarters in Karlsruhe.

Our new buildings are right on the A8 Autobahn, exit No. 42 (Karlsbad), where vou are more than welcome to visit us.

Sincerely,

Dr. Karl Spanner President

### Microstage fits just about anywhere - the new M-110 / M-111

In the past, travel range in the millimeter range with sub-micron resolution in a compact package was a recipe for trouble, at the very least when it came to motorizing the system. The new M-110 and M-111 micro-stages make this a thing of the past. This generation of motorized translators offers travel ranges from 5 to 15 mm in a package measuring only 62 x 60(70) x 20 mm. In closed-loop operation, the DC motor achieves speeds of up to 2.5 mm/s, minimal incremental motion of 0.05 µm and guiding accuracy of 1 µm. The central aperture in the platform and the XY, XZ and XYZ combinations make the system suitable for a wide range of applica-

M-110 / M-111 microstages with the specifications described above are ideal for use in photonics packaging, fiber positioning, quality control, and anywhere where precision positioning in tight guarters is required. In combination with PI's C-842 or C-844 controllers, or with the new C-880 multi-axis controller, the compact microstages offer inexpensive entry into the field of automated fiber positioning. Where higher resolutions are required, systems with piezoelectric drives can be added, such as the NanoCube seen in the picture.

#### M-110 / M-111 Microstages in industrial applications

Do you have

High duty-cycles? 24-hour operation?

7 davs/week, 365 davs/vear?

If the M-110 / M-111 looks like it would fit in your setup, then consider the version with low-friction recirculating ballscrew.

Call and discuss your application with a PI sales engineer.

### C-862 Mercury-the versatile DC-motor controller in a palm-top package

Small in size but big in performance: this is the unique Mercury DC-motor controller. Introduced nine months ago, the Mercury became an incomparable sales success within a few weeks. This controller is the optimal solution in a wide variety of motion control and positioning applications. Up to 16 Mercury controllers can be daisy-chain networked off a single RS-232 port. This and the many other features make the Mercury the fastest and most inexpensive solution for a host of automation tasks.

#### Have a look at these unique features:

- Buns DC-Motors up to 6 watt with internal amplifier
- Runs DC-Motors up to 60 watt with external amplifier
- Compatible with all PI stages
- Speed up to 60 mm/s
- Extensive command set
- P-I-D servo control
- Non-volatile storage of all system parameters
- Macro programmable
- Non-volatile storage of macros and parameters
- Autostart option to run a motion program at power-up without PC
- Digital I/O ports for internal /
- external triggering ■ Inputs for limit and position refer-
- ence sensors Output for control of motor brakes

The Mercury was developed for the OEM market with high volume, high performance and low price in mind. Now the Mercury is also available in small quantities at a very reasonable price level. The package also includes a widerange power supply, RS-232 cable, software and user manua



- Communication via RS-232 interface
- Networkable, with up to 16 Mercurys off one single RS-232 port
- Single-voltage operation, 12-15 VDC
- Extensive software for operation and programming, libraries for all Windows OS, LabView drivers

Aore information about Mercury controllers can be ound in the new PI Product Catalog on page 9-10. Or call PI and talk with one of our sales engineers











C-862 Mercury II: Network address settal by dip switches without opening the case



### M-501 a vertical stage for M-500 series

In the past, if you needed precise products and is sized for direct vertical motion and did not enough mounting on the M-511, M-521 and room to install a linear translator at M-531 platforms (no adaptor plate a 90-degree angle, then you had a required!). problem that could not be so without sacrificing precision. PI is offerring the M-501.

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### The NEW M-331 to M-333 series offers a wide

range of travel ranges and stage sizes for the widest variety of applications. They are based on the proven design of the M-105.

Of course, individual stages of the same size can easily be combined in any combination. In addition, any stage can be mounted on the nextlarger stage without an adapter plate.

#### All Stainless-Steel

All-stainless-steel construction and homogenious materials for the base, carriage, crossed roller bearings, guides and drive assure a maximum of stability and guiding accuracy, even under conditions of varying temperature.

In addition, the stages have a central open aperture throughout the entire travel range, a feature which is hardly standard on crossed-roller-bearing steel stages.

#### High Variety of Drives

PL offers the following alternative drives for most of the stages:

Differential micrometers for manual positioning with 0.1 µm resolution.

- Motorized micrometer drives, the DC-Mikes, for automated tasks for resolutions better than 1 µm.
- D Piezoelectric hybrid drives, the PiezoMikes, for even higher resolutions. PiezoMikes offer a "coarse" range of several millimeters and a fine range of 30 µm with a flexure-quided piezoelectric drive.

#### Alternatives in Aluminum

For applications where temperature changes are not an issue, versions will soon be available with aluminum bodies and carriages. Their advantage over their steel counterparts of the same size and travel range lies in their lower cost.

#### FIND PI AT

hotonics West, San Jose, CA (USA) January 22-24, 2002

At last!

volume of champaign.

remodeling existing undeveloped floorspace.

The new headquarters address is:

Biophysical Society 46<sup>th</sup> Annual Meeting, San Francisco February 24-26, 2002

OFC, Anaheim, CA (USA) March 19-21, 2002

Sensors, San Joce, CA (USA) May 21-23, 2002

CLEO, Long Beach, CA (USA) May 21-23, 2002

Semicon West, San Francisco, CA (IISA)

July 22-24, 2002 NFOEC, Dallas, TX (USA)

September 17-18, 2002

Diskcon, San Jose, CA (USA) September 18-19, 2002

Euspen in Eindhoven (NL) May 26-30, 2002

**INFMeeting 2002 in Bari (Italy)** June 24-28, 2002

BIAS 2002 in Milan (Italy) November 19-23, 2002

Drives & Controls in London (UK) March 13 -15 2002

Photonex in Coventry (UK) October 17-18, 2002

#### Hannover Messe (Germanv) April 15-20, 2002

Semicon Europe in München (Germany) April 16-18, 2002

Fiber Communication in München (Germany)

June 4-6, 2002 Actuator in Bremen (Germany)

June 18-21, 2002

November 12-15, 2002

Photonics Korea 2002, Seoul (Korea)

### Top precision now also available for shorter ranges

The M-505 now rounds out the M-500 series with travel ranges of 25, 50, 100 and 150 mm (1-6 in.). The result is a uniform series of models in varying sizes up to 300 mm (12 in.) travel range.

All the stages share the same degree of precision, and:

- Compact, low-profile design with integrated motor
  - Recirculating ballscrew drive for speeds of up to 50 mm/s or continuous operation
    - Hall-effect reference and limit switches
      - Active Drive<sup>™</sup> motor option
        - Stepper motor option

The M-505 series was designed for industrial use and is specified with an MTBF of > 20,000 hours. You can learn more about this product in our catalog, *MicroPositioning*, NanoPositioning, NanoAutomation, p. 7-38, or by visiting www.pi.ws

with travel ranges from 25 to 150 m (1-6 in.)





# Rotary stages with a new look

Introducing the new M-060, M-061 and M-062 rotary stages. These stages are equipped with a preloaded worm-gear drive to virtually eliminate backlash. The standard versions also have direction sensing and a non-contact Hall-effect reference switch which allows connection to the C-880 multi-axis motion controller. All PI motor types are available, from stepper motors, DC servo-motors to the optional ActiveDrive™ with IntelliStage™ compatibility.



June 10-12, 2002 **Optatec in Frankfurt (Germany)** electronica in München (Germany)

## PI Headquarters has moved

Thirty-five hundred truckloads of earth and exactly one year of construction later, in October 2001, PI's new headquarters building in Karlsruhe was virtually completed and finally occupied. The move also involved 70 movingvan loads for the manufacturing department alone, and an indeterminate

We now have 5700 square meters (61,300 sq. ft.) for administration, sales, development, and training alongside 7000 square meters (75,300 sq. ft.) for production. The production area can be doubled at a later date simply by

with a direct position feedback option, implemented by attaching the encoder directly to the rotor.

You can learn more about this product on p. 7-60 of our catalog, or by visiting **www.pi.ws** 

M-060, M-061 and



led with water-resistant cases and clean-air connections for protection agai the environment (grinding dust, water vapor, oil aerosols).

# Using piezo translators parallax error correction precision grinding

High-precision mechanical parts-especially parts in modern internal combustion engines-must be produced with very low tolerances. To meet these requirements, turned parts must be ground in a follow-up operation. During grinding, the grinding wheel rotates at high speed while the cylindrical part is rotated slowly. This process is generally plagued by an undesirable non-zero angle beween the workpiece axis and the grinding wheel axis.

The effect of this angle can be corrected as follows: First, a blank is ground and its deviation from a perfect cylinder is measured (parallax error). This error is then corrected using the appropriate micrometer screw.

The problem is that it is not possible to read out submicron settings with a micrometer screw, so numerous blanks have to be run in order to find the right position.

Here the advantages of piezoelectric translators can be used: with up to 0.2 mm travel range and high stiffness (several hundred newtons per micron), a piezo can resolve positions in the nanometer range. Linked to sensors, the piezo can move to within a few nanometers of a defined position repeatably. This means that production

can begin immediately after the first blank is measured and the piezo translator correspondingly initialized.

In this application, the piezo translator saves both time and materia

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# Piezo stages with E-710 digital control electronics

Increased performance

Optimum performance of the P-500

stages is achieved with the use of an

With the digital controller, the advan-

tages of the single-module design

can be fully realized and step-and-

settle controlled in all dimensions at

once. Not only can complex trajecto-

ries be realized, but thanks to rapid

The E-710 can optionally be equipped

with an ultra-fast PIO (parallel

input/output) interface. With a data

rate of 1 read or write operation per

microsecond, the PIO provides data

virtually in real-time. Such data can

include, for example, readout of posi-

tion values or input of signals from a

function generator (for scanning

applications) or target positions

generated by an external servo-loop.

For scanning applications, the

E-710.SCN software option is a clev-

erly thought out addition designed to

move a multi-dimensional piezo cap-

sensor stage (P-500 series, P-733,

etc.) along a scan line. Using a lea-

rning function, the operating volt-

ages are so controlled (Signal-

Preshaping<sup>™</sup>) that the stage motion

exactly follows the scan lines. The

great advantage here is that the

system figures out the optimal

servo-control parameters (which vary

Even without the function-generator

software option, optimal servo-loop

parameters can be entered using the

standard NanoCapture™ software.

according to load, etc.) all by itself.

sensor data transfer and high con-

with digital control

E-710 digital controller

The P-500 series has grown into a The resonant frequency and stiffness well-rounded collection of multi- of the various system axes vary conaxis piezo stages. They have the siderably from model to model. The same dimensions but different exact values are cited in the catalog. combinations of active axes, with Turn to your PI sales engineer for up to 6 degrees of freedom. The help in choosing the optimum optimal stage for a specific applica- system for your application. tion can be chosen from what are now 18 different models. Seventeen variants are described in detail in our 2001 catalog.

#### Positioning in 6 degrees of freedom

All models are single-module units (a single platform for motion in all directions, not a stacked system) and all are equipped with capacitive position feedback sensors.

The 6-axis versions are the P-517.6CD and P-527.6CD (table troller calculation speed, any crossbelow). A third 6-axis stage worthy talk effects can be effectively comof note, albeit with different dimen- pensated. For example, by adding Zsions, is the P-587.6CD, our long- axis control, out-of-plane motion distance runner with travel range of accompanying XY moves can be  $800 \times 800 \times 200 \ \mu m$  and  $\pm 500 \ \mu rad$ . reduced.





#### P-500 series a

|  | Х        | Υ        | Z        | $\theta_{\rm X}$ | $\theta_{\rm Y}$ | $\theta_z$   |  |
|--|----------|----------|----------|------------------|------------------|--------------|--|
| ravel range up to "  | 200 µm   | 200 µm   | 200 µm   | +/- 1 mrad       | +/- 1 mrad       | +/- 2 mrad   |  |
| Repeatability up to"   | +/- 1 nm | +/- 1 nm | +/- 1 nm | +/- 0.1 µrad     | +/- 0.1 µrad     | +/- 0.5 µrad |  |
| In multi-axis P-500 models. it is not alwavs possible to achieve these values one all axes at the same time. |          |          |          |                  |                  |              |  |

#### DECTO

| F-527.00D six-axi | is positioner a | nd scanner da | ta:      |                  |                  |            |
|-------------------|-----------------|---------------|----------|------------------|------------------|------------|
|                   | Х               | Υ             | Z        | $\theta_{\rm X}$ | $\theta_{\rm Y}$ | $\theta_z$ |
| Travel range      | 200 µm          | 200 µm        | 20 µm    | +/- 0,3 mrad     | +/- 0,3 mrad     | +/- 2 mrad |
| Repeatability     | +/- 10 nm       | +/- 10 nm     | +/- 5 nm | +/- 0.1 µrad     | +/- 0.1 µrad     | +/- 1 µrad |

P-5876CD six-axis NanoPositic with E-710.6CD digital electronic

#### E-710 general data

| Processor                                | DSP 32-bit floating point, |  |  |
|--|----------------------------|--|--|
| Sampling rate                            | 40 µs sensor 200 µs serv   |  |  |
| Effective resolution of D-to-A converter | 20 bits                    |  |  |
| Max. output power                        | 25 W per channel           |  |  |
| Average output power                     | 6 W per channel            |  |  |
| Max. output current <20 ms               | 200 mA per channel         |  |  |
| Average output current >20 ms            | 50 mA per channel          |  |  |
| Output voltage range                     | -20 V to +120 V            |  |  |

#### E-710 digital electronics model overview

E-710.4CL 4-channel controller with LEMO connectors

E-710.3CD 3-channel controller with sub-D connectors for ID-chip readout

E-710.4CD 4-channel controller with sub-D connectors for ID-chip readout

E-710.6CD 6-channel controller with sub-D connectors for ID-chip readout

E-710.P3D 3-channel controller with sub-D connectors and PIO Interface

E-710.P4D 4-channel controller with sub-D connectors and PIO Interface

E-710.SCN Software Option Internal function generator with learning function for scanning applications

> Systems with a multi-axis positione or scanner like the P-500 find applica tion in: Microscopy / scanning micro scopy: SNOM, AFM, E-beam (P-500 vacuum version). Semiconductor: mask positioning, vertical wafe ositioning, wafer stepping. Biotech ology, Medicine: cell tracking, nicroscopy, interferometry, surface profile mapping. Stages available for such applications include vacuum versions and, on request, non-mag netic versions.







loop on all channe