# S-340 Piezo Tip / Tilt-Platform High-Dynamics for Mirrors and Optics with a Diameter of up to 100 mm (4")



S-340 tip/tilt platform for mirrors with a diameter of up to 100 mm

- Resolution up to 20 nrad, Excellent Position Stability
- Optical Beam Deflection to 4 mrad
- Higher Precision and Dynamics via Parallel Kinematics
- Only One Moving Platform with a Fixed Pivot Point Prevents the Change of the Polarization
- Sub-ms Response
- For Mirrors with a Diameter up to 100 mm
- Position-Controlled Versions for Better Linearity
- Excellent Temperature Stability

S-340 tip/tilt platforms allow high-dynamic and precise angular movements of the top platform in two orthogonal axes with a common pivot point (parallel kinematics).

The systems are designed for mirrors with a diameter of up to

### **Application Examples**

- Image processing / stablilization
- Laser scanning / beam steering
- Active and adaptive optics
- Optical filters
- Beam stabilization
- Correction of polygon mirror errors

100 mm and their differential drive enables an outstanding angular stability in a wide temperature range. A variety of top platforms are available to achieve an optimum thermal adaptation to different mirror materials. For operation in closed-loop, the SD versions are equipped with high-resolution strain gauge sensors in a thermally stable circuit. All versions feature a sub-urad resolution and a tip/tilt range of 2 mrad (equivalent to 4 mrad optical beam deflection).

## Parallel-Kinematic Design for Improved Stability, Linearity and Dynamics

Piezo tip/tilt mirror systems of Pl are based on parallel kinematics with a single movable

## **Ordering Information**

#### S-340.A0L

Piezo Tip/Tilt Platform, 2 mrad, Open-Loop, LEMO Connector, Aluminum Top Plate

## S-340.ASL

Piezo Tip/Tilt Platform, 2 mrad, SGS, LEMO, Aluminum Top Plate

#### S-340.ASD

Piezo Tip/Tilt Platform, 2 mrad, SGS, Sub-D Connectors, Aluminum Top Plate

Various material for the top platforms are available on demand:

S-340.S0L / .SSL / .SSD: High-Grade Steel

S-340.T0L / .TSL / .TSD: Titanium

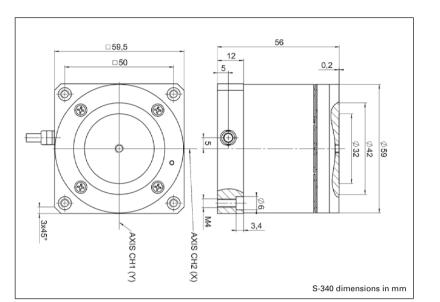
S-340.i0L / .iSL / .iSD: Invar

platform for all directions of motion. The four actuators are controlled differentially in pairs depending on the tip/tilt movement of the platform. This results in an excellent stability in linear and angular positioning for a wide temperature range. Compared to systems with an independent positioner per tilt axis, parallel-kinematics offer the advantage of symmetrical dynamic properties of motion for all axes, faster response and better linearity with a compact design. For this kind of design no change of polarization of the reflected light occurs, different than for stacked single axis systems like e.g. galvo scanners.

# Ceramic-Insulated Piezo Actuators Provide Superior Lifetime

The highest possible reliability is assured by employing the award-winning PICMA® multilayer piezo actuators. PICMA® actuators are the only actuators on the market with a ceramiconly insulation which makes them resistant to ambient humidity and leakage-current failures. They are thus far superior to conventional actuators in reliability and lifetime.







E-616 OEM steering mirror controller shown with the miniature S-334 tip/tilt mirror system

## **Technical Data**

Model	S-340.ASD/.ASL	S-340.A0L	Units	Tolerance
Active axes	θ Χ, θΥ	θΧ, θΥ		
Motion and Positioning				
Integrated sensor	SGS	-		
Open-loop tip/tilt angle, -20 to +120 V	2	2	mrad	min.
Closed-loop tip/tilt angle	2	-	mrad	
Open-loop tip/tilt angle resolution	0.02	0.02	µrad	typ.
Closed-loop tip/ tilt resolution	0.2	-	µrad	typ.
Linearity in θΧ, θΥ	0.1	-	%	typ.
Repeatability in θX, θY	0.15	-	µrad	typ.
Mechanical properties				
Unloaded resonant frequency ( $\theta X$ , $\theta Y$ )	1.4	1.4	kHz	±20 %
Resonant frequency loaded in $\theta X$ , $\theta Y$ (with glass mirror diameter 50 mm, thickness 15 mm)	0.9	0.9	kHz	±20 %
Resonant frequency loaded in θΧ, θΥ (with glass mirror diameter 75 mm, thickness 22 mm)	0.4	0.4	kHz	±20 %
Distance of pivot point to platform surface	7.5	7.5	mm	±1 mm
Platform moment of inertia	18000	18000	g · mm²	±20 %
Drive properties				
Ceramic type	PICMA®	PICMA®		
Electrical capacitance	6/axis	6/axis	μF	±20 %
Dynamic operating current coefficient	0.45/axis	0.45/axis	µA/(Hz ⋅ mrad)	±20 %
Miscellaneous				
Operating temperature range	-20 to 80	-20 to 80	°C	
Material case	Aluminum	Aluminum		
Material platform	Aluminum; or optionally Steel, Titanium or Invar	Aluminum; or optionally Steel, Titanium or Invar		
Mass	0.355	0.35	kg	±5 %
Cable length	2	2	m	±10 mm
Sensor/voltage connection	Sub-D connector / LEMO	LEMO		
Decement and examples ( even lifter				

Recommended controller / amplifier

Closed-loop versions with Sub-D connectors: E-616 servo controller for tip/tilt mirror systems s. p. 2-132; with LEMO connector: E-500 System s. p. 2-142. Open-loop: E-500 System s. p. 2-142.