

Fast, High-Load Hexapod for Dynamic Motion Simulation / Vibration Cancellation

FOR LOADS TO 60 KG

H-900KSCO

- + Low- wear, brushless DC motors
- + Travel ranges to 200 mm in X and Y and up to 170 mm in Z
- + Tilt and rotation angle to 66°
- + High velocities



Reference- class 6- axis positioning system

Parallel- kinematic design for six degrees of freedom making it significantly more compact and stiff than serial- kinematic systems, higher dynamic range, no moved cables: Higher reliability, reduced friction.

The H-900KSCO motion hexapod is designed for dynamic motion in all degrees of freedom (X,Y,Z, pitch, roll, yaw). With 130lbs payload and 80mm/sec max. velocity, it provides an excellent balance of speed and load capacity in a compact envelope. Applications of the H-900KSCO hexapod platform include motion cancellation, motion simulation (profiles compatible to ISO 20672, ISO 8728, and ISO 16328), industrial alignment processes, precision machining, automotive production, and stabilization of motion on moving vehicles and marine vessels.

Powerful digital controller, open software architecture

Optional: Software for avoiding collisions in restricted workspace



Specifications

| Preliminary Data | H-900KSCO | Unit | Tolerance |
|--|---|------------------|-----------|
| Active axes | X, Y, Z, θ_x , θ_y , θ_z | | |
| Motion and Positioning | | | |
| Single- actuator design resolution | 0.58 | μm | |
| Travel range* X, Y | 200 | mm | |
| Travel range* Z | 170 | mm | |
| Travel range* θ_x , θ_y | 66 | $^\circ$ | |
| Travel range* θ_z | 66 | $^\circ$ | |
| Min. incremental motion X, Y | 5 | μm | typ. |
| Min. incremental motion Z | 5 | μm | typ. |
| Backlash X, Y | 20 | μm | typ. |
| Backlash Z | 5 | μm | typ. |
| Backlash θ_x , θ_y | 50 | μrad | typ. |
| Backlash θ_z | 90 | μrad | typ. |
| Repeatability X, Y | ± 2 | μm | typ. |
| Repeatability Z | ± 0.5 | μm | typ. |
| Repeatability θ_x , θ_y | ± 5 | μrad | typ. |
| Repeatability θ_z | ± 9 | μrad | typ. |
| Max. velocity X, Y, Z | 80 | mm/ s | |
| Max. velocity θ_x , θ_y , θ_z | 520 | mrad/ s | |
| Typ. velocity X, Y, Z | 20 | mm/ s | |
| Typ. velocity θ_x , θ_y , θ_z | 130 | mrad/ s | |
| Mechanical Properties | | | |
| Load (base plate horizontal) | 635 | N | max. |
| Holding force, de- energized (base plate horizontal) | 635 | N | max. |
| Motor Type | DC gear motor | | |
| Miscellaneous | | | |
| Operating temperature range | -10 to 50 | $^\circ\text{C}$ | |
| Material | Aluminum | | |
| Mass | 65.5 | kg | |

Technical data specified at $20 \pm 3 \text{ }^\circ\text{C}$.

Ask about custom designs!

* The travel ranges of the individual coordinates (X, Y, Z, θ_x , θ_y , θ_z) are interdependent. The data for each axis in this table shows its maximum travel, where all other axes are at their zero positions. If the other linear or rotational coordinates are not zero, the available travel may be less.

Order Information

H-900KSCO

Motion Hexapod for 60 kg Load, to 200 mm Travel Range, to 80 mm/ s Velocity

Ask about custom designs!

Controllers / Drivers / Amplifiers

[C-887.5x Controller for Hexapod Positioning Systems](#)

Related Products

[H-850 6- Axis Hexapod](#)

[H-840 6- Axis Hexapod](#)

[H-845 High- Load Hexapod](#)

[H-860KMAG High- Dynamics Hexapod](#)